# Package 'FLightR'

July 4, 2024

Title Reconstruct Animal Paths from Solar Geolocation Loggers Data Version 0.5.5 Date 2024-06-28 **Description** Spatio-temporal locations of an animal are computed from annotated data with a hidden Markov model via particle filter algorithm. The package is relatively robust to varying degrees of shading. The hidden Markov model is described in Movement Ecology -Rakhimberdiev et al. (2015) <doi:10.1186/s40462-015-0062-5>, general package description is in the Methods in Ecology and Evolution -Rakhimberdiev et al. (2017) <doi:10.1111/2041-210X.12765> and package accuracy assessed in the Journal of Avian Biology -Rakhimberdiev et al. (2016) <doi:10.1111/jav.00891>. URL https://CRAN.R-project.org/package=FLightR BugReports https://github.com/eldarrak/FLightR/issues **Depends** R (>= 4.1.0) Imports bit, geosphere, ggmap, ggplot2, CircStats, circular, fields, maps, mgcv, nlme, parallel, RcppArmadillo, sf, suntools, truncnorm License GPL-3 ByteCompile true **Encoding UTF-8** RoxygenNote 7.3.1 Suggests covr, testthat, knitr, rmarkdown VignetteBuilder knitr NeedsCompilation no Author Eldar Rakhimberdiev [aut, cre], Anatoly Saveliev [aut], Julia Karagicheva [aut], Simeon Lisovski [ctb], Johannes de Groeve [ctb]

Type Package

2 BAStag2TAGS

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Repository CRAN

**Date/Publication** 2024-07-04 17:10:06 UTC

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# Description

this function converts combines twilights detected in BAStag with raw data and writes them down in TAGS format that can be easily read by get.tags.data

# Usage

```
BAStag2TAGS(raw, twl, threshold, filename = NULL)
```

# Arguments

raw	original data - dataframe with two columns first column must contain time and second measured light levels
twl	twilights object from preprocess.light function
threshold	threshold value used for twilight definition in preprocess light

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filename

if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS format will be written

#### **Details**

TAGS format returned or written as .csv by this function is a dataframe with columns

date time date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z

light light value measured by tag

twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)

excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)

interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

# Value

NULL if filename is provided or TAGS formatted dataframe.

# Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

#### See Also

twGeos2TAGS and GeoLight2TAGS

find.stationary.location

find unknown calibration location

# **Description**

Functions attempts to find a location where The function attempts to find a location for a time period assuming animal was not moving. Does not work well will shaded data!

# Usage

```
find.stationary.location(
   Proc.data,
   calibration.start,
   calibration.stop,
   plot = TRUE,
   initial.coords = NULL,
   print.optimization = TRUE,
   reltol = 1e-04
)
```

## **Arguments**

Proc.data processed data object generated by get.tags.data

calibration.start

POSIXct time when stationary period started

calibration.stop

POSIXct time when stationary period ended

plot plots every iteration

initial.coords location vector with initial values for location (longitude and latitude). Should be close (+-2000 km from the real location)

print.optimization

do you want every optimization iteration to be printed? If TRUE - Lon, Lat, calibration mean and calibration sd are being printed. Optimization tries to min-

imize the latter.

tolerance for optimization, see optim for more details

# Details

reltol

The idea behind the function is that it tries to minimize variance between slopes for the whole period by optimizing location. It can be seen as an extension of Hill-Ekstrom calibration idea.

## Value

vector with coordinates - longitude and latitude.

## Author(s)

Eldar Rakhimberdiev

## **Examples**

```
#this example takes about 15 minutes to run

File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)
plot_slopes_by_location(Proc.data=Proc.data, location=c(5.43, 52.93))
abline(v=as.POSIXct("2013-08-20", tz='GMT')) # end of first calibration period
abline(v=as.POSIXct("2014-05-05", tz='GMT')) # start of the second calibration period
Location<-find.stationary.location(Proc.data, '2013-07-20', '2013-08-20', initial.coords=c(10, 50))</pre>
```

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find.times.distribution

extracts times of arrival and departure to/from spatial extent

# **Description**

Idea of this functions is to extract schedules for known location

## Usage

```
find.times.distribution(Result, Spatial.Index)
```

# **Arguments**

Result FLightR result object obtained from run.particle.filter

Spatial.Index Row numbers for spatial grid (Result\$Spatial\$Grid) to estimate schedules

for.

## Value

dataframe with columns for 0.025, 0.25, 0.5, 0.75, 0.975 probability of line crossing and rows for every crossing.

## Author(s)

Eldar Rakhimberdiev

FLightR2Movebank

Summary of estimated locations for Movebank

# **Description**

Summarize result object in the format required for upload to Movebank

# Usage

```
FLightR2Movebank(Result, alpha = 0.5, filename = NULL)
```

# **Arguments**

Result FLightR result object obtained from run.particle.filter

alpha coverage of the credible intervals for now only two options: 0.95 or 0.5.

filename if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS

format will be written

GeoLight2TAGS

## **Details**

This function accepts FLightR results object.

#### Value

NULL if filename is provided or Movebank formatted dataframe.

#### Author(s)

Eldar Rakhimberdiev

GeoLight2TAGS	Function to write down twilights annotated in GeoLight package data
	in so-called TAGS format

# Description

this function converts combines twilights detected in BAStag to twGeos with raw data and writes them down in TAGS format that can be easily read by get.tags.data

#### Usage

```
GeoLight2TAGS(raw, gl_twl, threshold, filename = NULL)
```

## **Arguments**

raw original data - dataframe with two columns first column must contain time and

second measured light levels

gl\_twl twilights object from GeoLight

threshold threshold value used for twilight definition in GeoLight

filename if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS

format will be written

# Details

TAGS format returned or written as .csv by this function is a dataframe with columns

datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z

light light value measured by tag

twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)

excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)

interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

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#### Value

NULL if filename is provided or TAGS formatted dataframe.

#### Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

#### See Also

twGeos2TAGS and BAStag2TAGS

get.tags.data

read TAGS formatted data

## **Description**

Reads the data frame with detected twilight events into the FLightR

## Usage

```
get.tags.data(
  filename = NULL,
  start.date = NULL,
  end.date = NULL,
  log.light.borders = "auto",
  log.irrad.borders = "auto",
  saves = c("auto", "max", "mean"),
  measurement.period = NULL,
  impute.on.boundaries = FALSE
)
```

## **Arguments**

filename

the name of the file which the data are to be read from. File is supposed to be comma separated file of TAGS format. If it does not contain an absolute path, the file name is relative to the current working directory, getwd(). Tilde-expansion is performed where supported. This can be a compressed file (see file). Alternatively, file can be a readable text-mode connection (which will be opened for reading if necessary, and if so closed (and hence destroyed) at the end of the function call). File can also be a complete URL. For the supported URL schemes, see help for url.

start.date

date of beginning of relevant data collection in POSIXct format.

end.date

date of end of relevant data collection in POSIXct format.

log.light.borders

Numeric vector with length of 2 for minimum and maximum log(light) levels to use. Alternatively character value 'auto', that will allow FLightR to assign these values according to detected tag type.

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log.irrad.borders

Numeric vector with length of 2 for minimum and maximum log(irradiance) values to use. Alternatively character value 'auto', that will allow FLightR to assign these values according to detected tag type.

saves

character values informing FLightR if min or max values were used by logger.

measurement.period

Value in seconds defining how often tag was measuring light levels. If NULL value will be taken from known values for detected tag type.

impute.on.boundaries

logical, if FLightR should approximate values at boundaries. Set it to TRUE only if you have vary few active points at each twilight, e.g if tag was saving every 10 minutes or so.

#### **Details**

The returned object has many parts, the important are: (1) the recorded light data, (2) the detected twilight events, (3) light level data at the moment of each determined sunrise and sunset and around them (24 fixes before and 24 after), and (4) technical parameters of the tag, i. e. its type, saving and measuring period (the periodicity, in seconds, at which a tag measures and saves data).

#### Value

list, which is to be further processed with the FLightR.

## **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)</pre>
```

get\_ZI\_distances

Estimate distances moved between twilights

## **Description**

This function estimate distances with all zeros from stationary periods. This means many of the resulting movements will have 0 as the distance

## Usage

```
get_ZI_distances(Result)
```

## **Arguments**

Result

An object created by run.particle.filter.

## Value

a data frame containing median and quartiles for the distances and also departure and arrival time

make.calibration 9

## Author(s)

Eldar Rakhimberdiev

make.calibration Creates a calibration object, further used for calculation of coordinates in the run.particle.filter.

# **Description**

Function estimates all necessary parameters from the calibration data logged in a known location or locations.

# Usage

```
make.calibration(
  Proc.data,
  Calibration.periods,
  model.ageing = FALSE,
  plot.each = FALSE,
  plot.final = FALSE,
  likelihood.correction = "auto",
  fixed.logSlope = c(NA, NA),
  suggest.irrad.borders = FALSE,
  return.slopes = FALSE
)
```

## **Arguments**

Proc.data processed data object generated by get.tags.data

Calibration.periods

a data frame containing start and end dates of all the calibration periods (POSIXct) and geographic coordinates of the corresponding calibration locations.

and geographic coordinates of the corresponding campration location

model.ageing if set to TRUE, accounts for the tag ageing (with opacification of its transparent

shell of a light sensor), resulting into decreasing sensitivity of the device. This option is useful only if there were several calibration periods or if calibration

period was very long (~ longer than a month).

plot.each Do you want every twilight to be plotted while processing

plot.final Do you want final calibration graph to be plotted. On the graph you can see all

the observed versus expected light levels. All slopes should be similar.

likelihood.correction

will estimate correction of likelihood for the current calibration parameters. Highly recommended not to be change from 'auto'. In this case FLightR will switch it to FALSE in case tag saved data on 10 minutes or longer period.

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```
fixed.logSlope these are mean (1) and SD (2) for distribution of slopes. Should normally be estimated from the data (and thus default is c(NA, NA)). Change any of these two finite values if you want them to be predetermined and not estimated from the calibration data.

suggest.irrad.borders

experimental parameter! If set to TRUE function will try to find the best values for the log.irrad.borders

return.slopes if true function will return estimated individual twilight slopes.
```

## Value

calibration object to be uses in the make.prerun.object

#### Author(s)

Eldar Rakhimberdiev

## **Examples**

make.grid

makes spatial grid

# Description

This function makes a rectangular grid with use defined boundaries and probabilities of being stationary.

## Usage

```
make.grid(
  left = -180,
  bottom = -90,
  right = 180,
```

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```
top = 90,
distance.from.land.allowed.to.use = c(-Inf, Inf),
distance.from.land.allowed.to.stay = c(-Inf, Inf),
plot = TRUE,
return.distances = FALSE,
probability.of.staying = 0.5
)
```

## **Arguments**

```
left
                  - left boundary in degrees (-180 <= left <= 180)
                  - lower boundary in degrees (-90 <= bottom <= 90)
bottom
                  - right boundary in degrees (-180 <= right <= 180)
right
                  - top boundary in degrees (-90 <= right <= 90)
top
distance.from.land.allowed.to.use
                  - define how far from the shore animal could occur. Unit - km, negative values
                  are for inland and positive for offshore directions. Inf stays for infinity
distance.from.land.allowed.to.stay
                  - define how far from the shore animal could stay stationary between twilights.
                  Unit - km, negative values are for inland and positive for offshore directions.
                  Inf stays for infinity
                  show a plot of final grid.
plot
return.distances
                  - return distances to the shoreline
probability.of.staying
                  - assigned probability value for grid cells that do not satisfy distance.from.water.allowed.to.stay
```

#### Value

dataframe with coordinates(lon and lat) and probability.of.staying

## Author(s)

Eldar Rakhimberdiev

# **Examples**

```
Grid<-make.grid(left=-14, bottom=30, right=13, top=57,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))</pre>
```

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make.prerun.object

combines data, calibration and sets up priors

# **Description**

This function is one step before run.particle.filter. It combines data, calibration, spatial extent and movement priors and estimates spatial likelihoods that used later in the particle filter.

# Usage

```
make.prerun.object(
  Proc.data,
  Grid,
  start,
  end = start,
  Calibration,
  threads = -1,
  Decision = 0.05,
  Direction = 0,
  Kappa = 0,
  M.mean = 300,
  M.sd = 500,
  likelihood.correction = TRUE
)
```

#### **Arguments**

Proc.data	Processed data object created by get.tags.data.
Grid	Spatial grid created by make.grid.

start release location (lat, lon).

end end of the track location. Will use start by default. Use NA in case of unknown

end point.

Calibration Calibration object created by make.calibration.

threads number of parallel threads to use. default is -1, which means FLightR will use

all available threads except 1. Value 1 will force sequential evaluation

Decision prior for migration probability values from 0 to 1 are allowed

Direction Direction prior for direction of migration (in degrees) with 0 pointing to the

North

Kappa concentration parameter for vonMises distribution, 0 means uniform or even

distribution. Will set some prior for direction for all the track, so is not recom-

mended to be changed

M. mean Prior for mean distance travelled between consecutive twilights, km

M. sd Prior for sd of distance travelled between consecutive twilights, the higher the

value is the wider is the the distribution

likelihood.correction

Should likelihood correction estimated during make.calibration run be used?

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#### Value

Object to be uses in the run.particle.filter

#### Author(s)

Eldar Rakhimberdiev

## **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(
       calibration.start=NA,
       calibration.stop=as.POSIXct("2013-08-20", tz='GMT'),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
print(Calibration.periods)
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
```

map.FLightR.ggmap

plots result over map

## **Description**

plots track over map with probability cloud. Can plot only part of the track if dates are specified. Note that you can use it only after obtaining and registering in you current session Google Api Key. For details on the API key check [here](http://ornithologyexchange.org/forums/topic/38315-mapflightrggmap-error).

# Usage

```
map.FLightR.ggmap(
  Result,
  dates = NULL,
  plot.cloud = TRUE,
  map.options = NULL,
```

```
plot.options = NULL,
  save.options = NULL,
  zoom = "auto",
  return.ggobj = FALSE,
  seasonal.colors = TRUE,
  seasonal.donut.location = "topleft",
  seasonal.donut.proportion = 0.5,
  save = TRUE
)
```

# **Arguments**

Result	FLightR result object obtained from run.particle.filter			
dates	either NULL if all twilights should be included or data.frame with first column - start of the period and second end of the period. Each line represents a new period			
plot.cloud	Should probability cloud be plotted? If TRUE cloud is estimated by stat_density2d			
map.options	options passed to get_map, note that zoom option is defined separately			
plot.options	plotting options. Not defined yet!			
save.options	options passed to ggsave. Filename should be defined here.			
ZOOM	Zoom for map. If 'auto' FLightR will try to find optimal zoom level by downloading different size maps and checking whether all the points fit the map.			
return.ggobj	Should ggobj be returned for subsequent checks and/or replotting			
seasonal.colors				
	if true points of the track will have seasonal colors			
seasonal.donut.location				
	if NULL - no color wheel placed, otherwise select one of 'bottomleft', 'bottom-right', 'topleft'			
seasonal.donut.proportion				
	how much of X axis should color wheel occupy. return either NULL or ggplot2 class object			
save	should function save results with ggsave?			

## Value

if 'return.ggobj=TRUE' return ggplot object otherwise returns 'NULL'.

# Author(s)

Eldar Rakhimberdiev

# Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))
Calibration.periods<-data.frame(</pre>
```

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```
calibration.start=as.POSIXct(c(NA, "2014-05-05"), tz='GMT'),
       calibration.stop=as.POSIXct(c("2013-08-20", NA), tz='GMT'),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,</pre>
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
## Not run:
map.FLightR.ggmap(Result, seasonal.donut.location=NULL, zoom=6, save=FALSE)
## End(Not run)
# for this short track without variance seasonal donut does not work,
# but for normall track it will.
```

plot\_likelihood

plot likelihood surface over map

## Description

plots specific likelihood surface over map

## Usage

```
plot_likelihood(object, date = NULL, twilight.index = NULL)
```

# **Arguments**

object either output from make.prerun.object or run.particle.filter

date either NULL or a date (possibly with time) closest to the twilight you wan to be

plotted

twilight.index number of likelihood surface to be plotted

plot\_lon\_lat

#### **Details**

function plots likelihoods before particle filter run, so these are pure results of calibrations without any movement model

## Value

'NULL'

#### Author(s)

Eldar Rakhimberdiev

#### **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")</pre>
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))</pre>
Calibration.periods<-data.frame(</pre>
       calibration.start=as.POSIXct(c(NA, "2014-05-05"), tz='GMT'),
       calibration.stop=as.POSIXct(c("2013-08-20", NA), tz='GMT'),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,</pre>
 distance.from.land.allowed.to.use=c(-Inf, Inf),
 distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
plot_likelihood(all.in, twilight.index=10)
```

plot\_lon\_lat

plots result by longitude and latitude

## **Description**

This function plots result by latitude and longitude in either vertical or horizontal layout.

# Usage

```
plot_lon_lat(Result, scheme = c("vertical", "horizontal"))
```

## **Arguments**

Result FLightR result object obtained from run.particle.filter

scheme either 'vertical' or 'horizontal' layouts

#### Value

'NULL'

## Author(s)

Eldar Rakhimberdiev

## **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")</pre>
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(</pre>
       calibration.start=as.POSIXct(c(NA, "2014-05-05"), tz='GMT'),
       calibration.stop=as.POSIXct(c("2013-08-20", NA), tz='GMT'),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
 distance.from.land.allowed.to.use=c(-Inf, Inf),
 distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
plot_lon_lat(Result)
```

```
plot_slopes_by_location
```

plots log of observed versus expected slope by time for a known location

## **Description**

The function calculates and plots calibration slopes for sunsets and sunrises for every day of the tracking period, based on the assumption that the tag remained in the same (calibration) location all the time.

#### Usage

```
plot_slopes_by_location(
   Proc.data,
   location,
   log.light.borders = "auto",
   log.irrad.borders = "auto",
   ylim = NULL,
   xlim = NULL
)
```

# **Arguments**

Proc.data processed data object generated by get.tags.data

location vector with longitude and latitude of calibration location (degrees).

log.light.borders

numeric vector with length of 2 for minimum and maximum log(light) levels to

use. Default value 'auto', will take these values from the Proc.data object.

log.irrad.borders

numeric vector with length of 2 for minimum and maximum log(irradiance)

values to use. Default value 'auto', will take these values from the Proc.data

object.

ylim the y limits of the plot. The default value, NULL, indicates that the range of the

finite values to be plotted should be used.

x1im the x limits of the plot. The default value, NULL, otherwise can be POSIXct or

character in a form readable by as.POSIXct.

#### **Details**

The plot of calibration slopes is used for finding start and end dates of a calibration period (the time period, during which the tag remained in the calibration location with coordinates (x,y)). During the calibration period, the calibration slopes vary little both, between the twilight events (sunrises and sunsets) and in time. When the tag changes location, the slopes for sunrises and sunsets start to deviate. There may potentially be several calibration periods for the same location (if the bird returned to the same location several times). The boundaries (start and end dates) of each of these periods are captured visually. If there were more than one calibration location, the procedure is repeated, once for each location. All the obtained calibration periods can be entered in a data frame 'Calibration.periods', for further analysis. Each line of the data frame contains start and end dates (if applicable) of the calibration period and geographic coordinates of the location.

## Value

'NULL'

plot\_util\_distr 19

#### Author(s)

Eldar Rakhimberdiev

## **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)
plot_slopes_by_location(Proc.data=Proc.data, location=c(5.43, 52.93))
abline(v=as.POSIXct("2013-08-20", tz='GMT')) # end of first calibration period
abline(v=as.POSIXct("2014-05-05", tz='GMT')) # start of the second calibration period</pre>
```

plot\_util\_distr

plots resulting track over map with uncertainty shown by space utilisation distribution

# Description

May be use not only for the whole track but for a set of specific dates, e.g. to show spatial uncertainty during migration. Note that you can use it only after obtaining and registering in you current session Google Api Key. For details on the API key check [here](http://ornithologyexchange.org/forums/topic/38315-mapflightrggmap-error).

#### Usage

```
plot_util_distr(
   Result,
   dates = NULL,
   map.options = NULL,
   percentiles = c(0.4, 0.6, 0.8),
   zoom = "auto",
   geom_polygon.options = NULL,
   save.options = NULL,
   color.palette = NULL,
   use.palette = TRUE,
   background = NULL,
   plot = TRUE,
   save = TRUE
```

#### **Arguments**

Result

FLightR result object obtained from run.particle.filter

dates

Use NULL if all twilights will be used for plotting, one integer if specific twilight should be plotted (line number in Result\$Results\$Quantiles). Use data.frame with first column - start of the period and second - end of the period and each line represents a new period to plot specific periods, e.g. wintering or migration.

20 plot\_util\_distr

options passed to get\_map, note that zoom option is defined separately map.options Probability breaks for utilisation distribution percentiles Zoom for map. If 'auto' FLightR will try to find optimal zoom level by downzoom loading different size maps and checking whether all the points fit the map. geom\_polygon.options options passed to geom\_polygon save.options options passed to ggsave. Filename should be defined here. color.palette colors for probability contours. Either NULL or colorRampPalette object use.palette should the same colors be used for polygon boundaries as for polygon filling? background if provided will be used as a background. Must be created by link[ggmap]{get\_map} plot should function produce a plot?

#### Value

save

list with two parts

res\_buffers spatial buffers for defined probability values

should function save results with ggsave?

p ggplot object

#### Author(s)

Eldar Rakhimberdiev

# **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")</pre>
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))
Calibration.periods<-data.frame(
       calibration.start=as.POSIXct(c(NA, "2014-05-05"), tz='GMT'),
       calibration.stop=as.POSIXct(c("2013-08-20", NA), tz='GMT'),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93, 52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=1)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run
```

run.particle.filter 21

run.particle.filter Run Particle Filter

## **Description**

Main function of FLightR, it takes fully prepared object created by make.prerun.object and produces a result object that can be used for plotting etc.

## Usage

```
run.particle.filter(
 all.out,
  cpus = NULL,
  threads = -1,
  nParticles = 1e+06,
 known.last = TRUE,
 precision.sd = 25,
 behav.mask.low.value = 0,
  k = NA,
 plot = TRUE,
  cluster.type = "PSOCK",
  a = 45,
 b = 1500,
  L = 90,
  adaptive.resampling = 0.99,
  check.outliers = FALSE,
  sink2file = FALSE,
  add.jitter = FALSE
)
```

## **Arguments**

all.out An object created by make.prerun.object.

cpus another way to specify threads

threads An amount of threads to use while running in parallel. default is -1. if value 1 submitted package will run sequentially

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nParticles total amount of particles to be used with the run. 10 000 (1e4) is recommended

for the preliminary run and 1 000 000 (1e6) for the final

known.last Set to FALSE if your bird was not at a known place during last twilight in the

data

precision.sd if known.last then what is the precision of this information. Will be used to

resample particles proportionally to their distance from the known last point

with probability P = dnorm(0, precision.sd)

behav.mask.low.value

Probability value that will be used instead of 0 in the behavioural mask. If set to

1 behavioural mask will not be active anymore

k Kappa parameter from vonMises distribution. Default is NA, otherwise will

generate particles in a direction of a previous transitions with kappa = k

plot Should function plot preliminary map in the end of the run?

cluster.type see help to package parallel for details

a minimum distance that is used in the movement model - left boundary for trun-

cated normal distribution of distances moved between twilights. Default is 45

for as default grid has a minimum distance of 50 km.

b Maximum distance allowed to fly between two consecutive twilights

how many consecutive particles to resample

adaptive.resampling

Above what level of ESS resampling should be skipped

check.outliers switches ON the online outlier routine

sink2file will write run details in a file instead of showing on the screen add.jitter will add spatial jitter inside a grid cell for the median estimates

#### Value

FLightR object, containing output and extracted results. It is a list with the following elements

Indices List with prior information and indices

Spatial Spatial data - Grid, Mask, spatial likelihood

Calibration all calibration parameters

Data original data

Results The main results object. Main components of it are

Quantiles dataframe containing results on locations. Each line corresponds to

a twilight

**Movement.results** dataframe containing all the movement results, Note - time at line n means time of the end of transition between n and n-1

outliers id of twilights excluded by online outlier detection tool

LL -Log likelihood

**Points.rle** run length encoding object with posterior distribution for every twilight. Note that numbers of points correspond to line numbers in \$Spatial\$Grid

**Transitions.rle** run length encoding object with all the transitions

#### Author(s)

Eldar Rakhimberdiev

## **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")</pre>
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))</pre>
Calibration.periods<-data.frame(
       calibration.start=NA,
       calibration.stop=as.POSIXct("2013-08-20", tz='GMT'),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
print(Calibration.periods)
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run.
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
```

```
stationary.migration.summary
```

find potential stationary periods and estimates their location and movement schedule

## **Description**

This function will find any sites where birds stayed longer than min.stay. Potential movement is detected by the minimum probability of movement prob.cutoff.

#### Usage

```
stationary.migration.summary(Result, prob.cutoff = 0.1, min.stay = 3)
```

# **Arguments**

Result FLightR result object obtained from run.particle.filter

prob.cutoff Minimum probability that defines movement

min.stay Minimum duration of stationary period (in twilights)

#### Value

list with stationary and movement statistics

#### Author(s)

Eldar Rakhimberdiev

# **Examples**

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))</pre>
Calibration.periods<-data.frame(</pre>
       calibration.start=as.POSIXct(c(NA, "2014-05-05"), tz='GMT'),
       calibration.stop=as.POSIXct(c("2013-08-20", NA), tz='GMT'),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
 distance.from.land.allowed.to.use=c(-Inf, Inf),
 distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=1)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run.
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
Summary<-stationary.migration.summary(Result, prob.cutoff=1)</pre>
# Use lower cut offs for real runs!
```

twGeos2TAGS 25

twGeos2TAGS	Function to write down twilights annotated in twGeos package data in so-called TAGS format

## **Description**

this function converts combines twilights detected in twGeos with raw data and writes them down in TAGS format that can be easily read by get.tags.data

# Usage

```
twGeos2TAGS(raw, twl, threshold, filename = NULL)
```

# **Arguments**

raw original data - dataframe with two columns first column must contain time and

second measured light levels

twl twilights object from preprocess.light function

threshold threshold value used for twilight definition in preprocess.light

filename if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS

format will be written

#### **Details**

TAGS format returned or written as .csv by this function is a dataframe with columns

datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z

light light value measured by tag

twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)

excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)

interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

# Value

NULL if filename is provided or TAGS formatted dataframe.

#### Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

#### See Also

BAStag2TAGS and GeoLight2TAGS

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